**Progress Report**

From: Adanegbe Amadasun

Cc: Alisha Singh Chauhan

Dear Sir,

This is our email regarding progress report and the milestone we have covered so far on our project.

We now have a better understanding on how to go about our project. We worked with Vlad last week Friday to accomplish various task for our project such as:

* Tuning our stepper driver to allow 0.6 ohms of current
* Drilling a hole through our case for the pulling system
* We also learnt how to cripple wires, we crippled our stepper motor wire to make it easier to connect it to ramp shield.

We have built a case for our FarmBot and are still working on creating our pulley system. Also, we had success in uploading teacup firmware into our Arduino for the pulley system, and we are currently trying to figure out the distance to use for stepper more to move.

Sincerely,

Adanegbe Amadasun